1 <u>Original Research Article</u> 2 D-optimal Exact Design: Weighted Variance Approach and 3 a Continuous Search Technique

By

5 Abstract

4

6 The convergence to a D-optimum measure is possibly obtained using a continuous search
7 technique while relying on the weighted variance approach. This search technique compares
8 favourably well with other known sequential search technique.

9 Keywords: Weighted Variance, D-optimum, Gradient Vector and Variance Function

10 1 Introduction

The weighted variance approach that obtains the optimum of a response function defined within a feasible region follows a sequential method. The aim of this research is to show that the continuous search technique Onukogu et al. (2002) relying on the weighted variance approach obtains the D-optimum exact design for a feasible region.

15 In the literature, the best D-optimal design can be selected within a design region with the aid of a combinatorial algorithm Iwundu et al. (2012). However, Wynn (1970) defined a 16 17 sequential addition of points to a given initial design in approaching a D-optimum design measure. Wynn further explained that a design is D-optimum if the determinant of the 18 information matrix is maximized. Thus, rather than a sequential search from an initial design, the 19 search technique reported in this research simply uses a non-sequential approach to obtain an N-20 point trial D-optimal design from the \overline{N} support points and subject the design measure to the 21 weighted variance approach to obtain a D-optimum design for a response function. 22

23

2 Weighted Variance Approach

24 2.1) Let f(x) be an n-variate, p-parameter polynomial of degree m, given by

25
$$f(x) = \underline{a}' \underline{x} + e;$$

26 <u>*a*</u> is a *p*-component vector of known coefficients, $\underline{x} \in \widetilde{X}$ (feasible region)

27 2.2) Define the n-component gradient vector,

28
$$\underline{g} = \{\partial f(x) / \partial x_i\} = \begin{pmatrix} g_1(x) \\ \vdots \\ g_n(x) \end{pmatrix}; g_i(x) = \underline{q}' \underline{x} + u;$$

29 where $g_i(x)$ is an (m-1) degree polynomial, i = (1, n)

- 30 \underline{q} is r-component vector of known coefficients.
- 31 Then compute the gradient vectors, $\{\underline{g}_i\}_{i=(1,N)}$
- 32 2.3) From \widetilde{X} , define the design measure,

33
$$\boldsymbol{\xi}_{N} = \begin{pmatrix} \underline{x}_{1} \boldsymbol{y}_{N} \\ \vdots \\ \underline{x}_{N} \boldsymbol{y}_{N} \end{pmatrix}; \underline{x}_{i} = (x_{i1}, \dots, x_{in});$$

- 34 where the N points are spread evenly in \widetilde{X} .
- 35 2.4) From (2.2) and (2.3) obtain the design matrix

36
$$X(\xi_N) = \begin{pmatrix} x_{11} \cdots x_{1r} \\ \vdots \\ x_{Ni} \cdots x_{Nr} \end{pmatrix} = \begin{pmatrix} x' \\ \vdots \\ \vdots \\ \vdots \\ \vdots \\ x' \\ x' \\ N \end{pmatrix}$$

and compute, the arithmetic mean vector $\underline{\overline{x}}_{A} = (\underline{\overline{x}}_{1}, \underline{\overline{x}}_{2}, \dots, \underline{\overline{x}}_{n}); \underline{\overline{x}}_{i} = \sum_{j=1}^{N} x_{ij} / N$

38
$$M^{-1}(\xi_N)$$
 and the variances $\{V_i\}_{i=(1,N)}; V_i = \underline{x}_i M^{-1}(\xi_N) \underline{x}_i, M(\xi_N) = X'(\xi_N) X(\xi_N)$

39 2.5) Define the direction vector,

40
$$\underline{d}_{A} = \sum_{i=1}^{N} \theta_{i} \underline{g}_{i}; \theta_{i} \in (0,1), \sum_{i=1}^{N} \theta_{i} = 1$$

41 and its variance $V(\underline{d}_A) = \sum_{i=1}^{N} \theta_i^2 V_i$

42 2.6) Solve for $\{\theta_i\}_{i=(1,N-1)}$ from the partial derivatives

43
$$\partial V(\underline{d}_A) / \partial \theta_i = 0; \theta_N = 1 - \sum_{i=1}^{N-1} \theta_i$$

44 and normalize to
$$\theta_i^* = \theta_i \left(\sum_{i=2}^N \theta_i^2\right)^{-\frac{1}{2}}; \sum_{i=1}^N \theta_i^{*2} = 1$$

45 2.7) Define the vector

46
$$\underline{d}_{A} = \sum_{i=1}^{N} \theta_{i}^{*} \underline{g}_{i} \text{ and normalize to } \underline{d}_{A}^{*}; \underline{d}_{A}^{*} \underline{d}_{A}^{*} = 1$$

47 2.8) Set the starting point,

- 48 $\underline{\overline{x}} = \underline{\overline{x}}_A$; which corresponds to the mean arithmetic vector
- 49 2.9) Compute the step-length,

50
$$\rho = \rho_A = \min_{\rho} d(\underline{a}'(\underline{x}_A + \rho \underline{d}_A^*))/d\rho = 0$$

51 2.10) move to $\underline{x}_A = \overline{\underline{x}}_A + \rho_A \underline{d}_A^*$, and at the jth step, to

52
$$\underline{x}_{Aj} = \underline{\overline{x}}_{Aj-1} + \rho_{Aj-1} \underline{d}_{Aj-1}^{*}$$

- 53 and compute, $f(\underline{x}_{Aj})$
- 54 2.11) Is $\left\|f(\underline{x}_{Aj}) f(\underline{x}_{Aj-1})\right\| \leq \delta$?
- 55 Yes: Set $\underline{x}_{Aj-1} = \underline{x}^*$, the maximize and stop,

56 No: Define,
$$\xi_{N+1}^{(0)} = \begin{pmatrix} \xi_N^{(0)} \\ \cdots \\ \underline{x}_{j-1} \end{pmatrix}$$
 and return to (2.3)

57 3. A Continuous Search Technique for an N-Point D-Optimal Exact Design

58 We shall rely on the search technique developed Onukogu et al. (2002) as follows:

59 The space of possible trials is defined by

$$\widetilde{X} = \{x_i; a_i \le x_i \le b_i \forall i = 1, 2, \dots, n\}$$

and the sequence of steps required to obtain the design are as follows:

a) Initial Design: Assuming f(.) to be a p-parameter m-degree polynomial surface, using a
 non-sequential method, obtain a non-singular p-point design

$$\boldsymbol{\xi}_{p} = \begin{cases} \underline{x}_{1}, \underline{x}_{2}, \dots, \underline{x}_{p} \\ W_{1}, W_{2}, \dots, W_{p} \end{cases}$$

64

65 Such that all the support points in ξ_p fall within the feasible region \widetilde{X} .

66 b) Regression Model of Variance Function

67 Define a p-parameter polynomial regression function of degree 2m,

68
$$y(\underline{x}) = b_{00} + \sum_{i=1}^{n} b_{10} x_i + \sum b_n x_i x_j + \dots + \sum_{i=m}^{n} \overline{b}_{mn} x_i^{2m}$$

69 where
$$y(\underline{x}) = d(\underline{x}_p, \xi_p) = \underline{x}'_j M^{-1}(\xi_p) \underline{x}_j; \underline{x}_j \in \widetilde{X} : j = 1, 2, ..., \overline{N}, \overline{N} \ge q \ge p$$

70
$$\underline{b} = (b_{00}, b_{10}, \dots, b_{n0}, \dots, \overline{b}_{m0}, \dots, \overline{b}_{mn})$$

The \overline{N} support points are normally inclusive of the initial p-points and are well-spread out as to be representative of \widetilde{X} .

73 c) Trial D-optimal Exact Design

74 The design ξ_N^{0} is achieved if

75 a.
$$\sum_{i=j}^{p} x_{ij}^{2}$$
 is maximum $\forall j = 1, 2, ..., p$

76 b.
$$\left\| \sum_{i=1}^{j} x_{ij} \right\|, \left\| \sum_{i=1}^{j} x_{ij} x_{ij} \right\|$$
, etc... are respectively minimized $\forall j, j < j$

77

Thus an N-point design from the \overline{N} support points and designated as

78
$$\xi_N^{(0)} = \begin{cases} \underline{x}_1, \underline{x}_2, \dots, \underline{x}_m, \dots, \underline{x}_N \\ W_1, W_2, \dots, W_m, \dots, W_N \end{cases}$$

79 d) Estimation of Regression Function

80 By the method of least squares applied to the data in step (b) above, compute the 81 estimates $\hat{\underline{b}}$ and $\hat{y} = X \hat{\underline{b}}$.

82 e) Global Maximum of \hat{y}

83 Obtain the global maximum \underline{x}^* of \hat{y} using the variance modulated technique and compute

84
$$d(\underline{x}^{*}, \xi_{N}^{(0)}) = \underline{x}^{*} M^{-1}(\xi_{N}^{(0)}) \underline{x}^{*}$$
 and

85
$$d(\underline{x}_{m},\xi_{N}^{(0)}) = \underline{x}_{m}' M^{-1}(\xi_{N}^{(0)}) \underline{x}_{m} = \min_{x} \{ \underline{x}' M^{-1}(\xi_{N}^{(0)}) \underline{x} \}; \ \underline{x} \in \xi_{N}^{(0)}$$

86 f) A Check for Optimality

87 Is
$$d(\underline{x}^*, \xi_N^{(0)}) \ge d(\underline{x}_m, \xi_N^{(0)})$$
?

88 No: Stop
$$\xi_N^{(0)}$$
 is D-optimal

89 Yes: set $\underline{x}^* = \underline{x}_m$, $w^* = w_m$ in $\xi_N^{(0)}$ and return to step (e) above.

90 4. ILLUSTRATIVE EXAMPLE

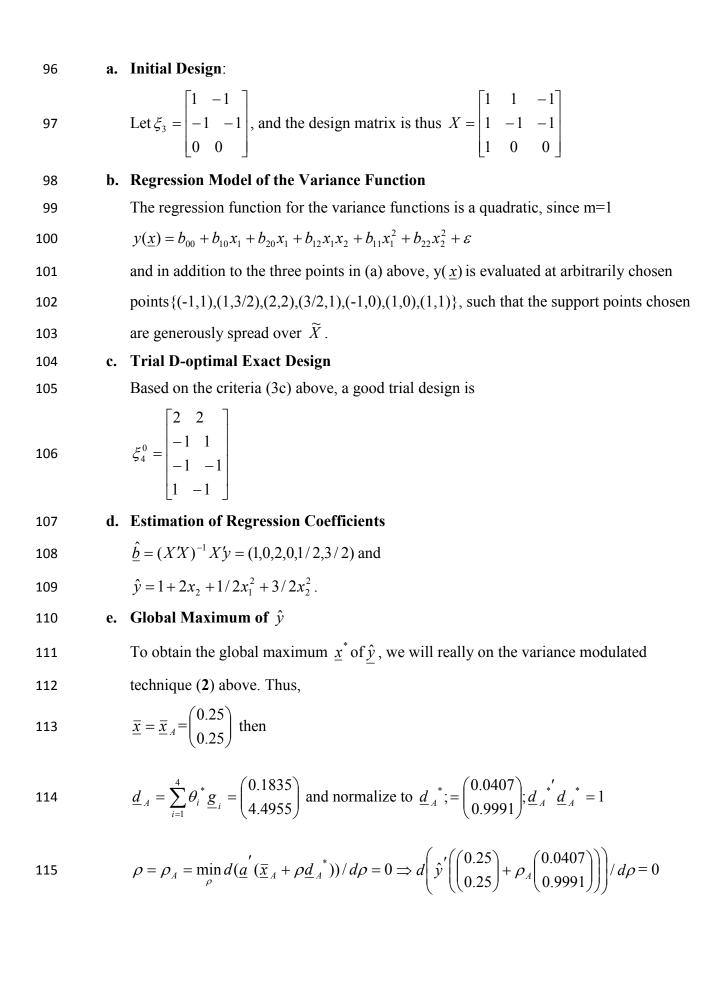
91 Obtain a 4-point D-optimal exact design for the response function

92
$$f(x_1x_2) = b_0 + b_1x_1 + b_2x_2 + \varepsilon$$

93 Subject to
$$\widetilde{X} = \{(x_1, x_2) = (-1, 1), (-1, -1), (1, -1), (0, 0), (1, 1), (2, 2)\}$$

94

95 Solution



116	i	$2.7575 + 2.9962 \rho_A = 0 \implies \rho_A = -0.9203$		
117	,	$\underline{x}_{A} = \underline{\overline{x}}_{A} + \rho_{A} \underline{d}_{A}^{*}$		
118	f)	A Check for Optimality		
119)	The minimum variance in table 1, is		
120)	$\underline{x}_{m} = (1, -1, -1), d(\underline{x}_{m}, \xi_{4}^{(0)}) = 0.5789$		
121		while $d(\underline{x}^{*}, \xi_{4}^{(0)}) = 0.3954$; therefore		
122		Is $d(\underline{x}^*, \xi_4^{(0)}) \ge d(\underline{x}_m, \xi_4^{(0)})$?		
123	1	No: Stop $\xi_4^{(0)}$ is D-optimal		
124	Ļ	Yes: set $\underline{x}^* = \underline{x}_m$, $w^* = w_m$ in $\xi_4^{(0)}$ and return to step (e) above.		
125	5	Conclusion		
126	A cor	A continuous search technique has been shown to have the canacity to obtain		

A continuous search technique has been shown to have the capacity to obtain D-optimum exact
design of a response function relying on the weighted variance approach within a feasible region.
This technique is very effective for obtaining optimal design in both block and non-block
experiments for a feasible region.

130 **6** Reference

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143Table 1: The table showing design points, gradient vector, variance and weighting factor144at N=4 design points in the feasible region.

Serial	Design Points	Gradient Vector	Variance	Weighting
	(x_{1i}, x_{2i})	$\underline{g}_i = (g_{1i}, g_{2i})$	(V_i)	Factor (θ_i^*)
1	2,2	2,8	0.8947	0.4034
2	-1 , 1	-1 , 5	0.7631	0.4731
3	-1 , -1	-1 , -1	0.5789	0.6237
4	1 , -1	1 , -1	0.7631	0.4735

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