



SDI Review Form 1.6

Journal Name:	Physical Science International Journal
Manuscript Number:	_2015_PSIJ_18253
Title of the Manuscript:	Robustness Analysis of a Closed-Loop Controller for a Robot Manipulator in Real Environments
Type of the Article	

General guideline for Peer Review process:

This journal's peer review policy states that **NO** manuscript should be rejected only on the basis of '**lack of Novelty**', provided the manuscript is scientifically robust and technically sound.

To know the complete guideline for Peer Review process, reviewers are requested to visit this link:

(<http://www.sciencedomain.org/page.php?id=sdi-general-editorial-policy#Peer-Review-Guideline>)



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PART 1: Review Comments

	Reviewer's comment	Author's comment (if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)
Compulsory REVISION comments	The plagiarism is also not found upto the best of my knowledge. The paper is well written. I recommend it for publication as it is.	Thank you
Minor REVISION comments		
Optional/General comments		