## SDI FINAL EVALUATION FORM 1.1

**PART 1:**

| Journal Name: | **Physical Science International Journal** |
|---|---|
| Manuscript Number: | **2015_PSIJ_18253** |
| Title of the Manuscript: | **Robustness Analysis of a Closed-Loop Controller for a Robot Manipulator in Real Environments** |
| Type of Article | **Review Article** |

**PART 2:**

| FINAL EVALUATOR'S comments on revised paper (if any) | Authors' response to final evaluator's comments |
|---|---|
| **Additional references were included in order to cite some contributions that consider robustified control techniques.**<br>**The authors attended all the comments and suggestions of the initial revision of the manuscript. An additional reference could be considered to exemplify the application of robust controllers of robotic manipulators:** Robust generalized predictive control of the Orthoglide robot, Fabian Andres Lara-Molina , João Maurício Rosário , Didier Dumur , Philippe Wenger<br>Industrial Robot: An International Journal 2014 41:3 , 275-285<br><br>**The reviewer** expresses my thanks for take part in revision of this manuscript. | |

**Reviewer Details:**

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|---|---|
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