



SDI Review Form 1.6

Journal Name:	Physical Science International Journal
Manuscript Number:	_2015_PSIJ_18253
Title of the Manuscript:	Robustness Analysis of a Closed-Loop Controller for a Robot Manipulator in Real Environments
Type of the Article	

General guideline for Peer Review process:

This journal's peer review policy states that **NO** manuscript should be rejected only on the basis of '**lack of Novelty**', provided the manuscript is scientifically robust and technically sound.

To know the complete guideline for Peer Review process, reviewers are requested to visit this link:

(<http://www.sciencedomain.org/page.php?id=sdi-general-editorial-policy#Peer-Review-Guideline>)



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PART 1: Review Comments

	Reviewer's comment	Author's comment <i>(if agreed with reviewer, correct the manuscript and highlight that part in the manuscript. It is mandatory that authors should write his/her feedback here)</i>
<u>Compulsory</u> REVISION comments		
<u>Minor</u> REVISION comments	(1) There are some errors in the formulas, such as $T(s)-S(s)=1$; (2) There are a lot of repetitions in Section 2; (3) Some other robustness control methods should be reviewed in the introduction; (4) The figures in the paper are unclear.	
<u>Optional/General</u> comments		

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