



SDI FINAL EVALUATION FORM 1.1

PART 1:

Journal Name:	Physical Science International Journal
Manuscript Number:	2015_PSIJ_18253
Title of the Manuscript:	Robustness Analysis of a Closed-Loop Controller for a Robot Manipulator in Real Environments
Type of Article	Review Article

PART 2:

FINAL EVALUATOR'S comments on revised paper (if any)	Authors' response to final evaluator's comments
Accept	

Reviewer Details:

Name:	Raquel Dormido Canto
Department, University & Country	Informática y Automática, National University of Distance Education, Spain